

MELSEC A Series

Programmable Logic Controller

User's Manual
(Hardware)

AD75M1/M2/M3 Positioning Module

● SAFETY PRECAUTIONS ●

(Always read before starting use)

When using Mitsubishi equipment, thoroughly read this manual and the associated manuals introduced in this manual. Also pay careful attention to safety and handle the module properly.

These precautions apply only to Mitsubishi equipment. Refer to using CPU module user's manual for a description of the PLC system safety precautions.

These ●SAFETY PRECAUTIONS● classify the safety precautions into two categories: "DANGER" and "CAUTION".




DANGER

Procedures which may lead to a dangerous condition and cause death or serious injury if not carried out properly.



CAUTION

Procedures which may lead to a dangerous condition and cause superficial to medium injury, or physical damage only, if not carried out properly.

Depending on circumstances, procedures indicated by  **CAUTION** may also be linked to serious results.

In any case, it is important to follow the directions for usage.

Store this manual in a safe place so that you can take it out and read it whenever necessary. Always forward it to the end user.

[DESIGN PRECAUTIONS]

DANGER

- Configure a safety circuit so that the safety of the overall system is maintained even when an external power error or PLC error occurs.
An accident may occur by a false output or a malfunction.
 - (1) Outside of the PLC, construct mechanical damage preventing interlock circuits such as emergency stop, positioning upper and lower limit switches.
 - (2) During zero return operation, the module is controlled by two data: zero return direction and zero return speed, and speed begins to decelerate when the near point dog turns on. If the zero return direction is set incorrectly, the module may continue to operate without decelerating. To prevent damage to the module in such cases, configure an interlock circuit outside the PLC.

CAUTION

- Do not bunch the control wires or communication cables with the main circuit or power wires, or install them close to each other.
They should be installed 100 mm (3.9 inch) or more from each other.
Not doing so could result in noise that would cause malfunction.

[INSTALLATION PRECAUTIONS]

CAUTION

- Use the PLC in an environment that meets the general specifications contained in this manual. Using this PLC in an environment outside the range of the general specifications could result in electric shock, fire, malfunction, and damage to or deterioration of the product.
- Insert the tabs at the bottom of the module into the mounting holes in the base module, and tighten the screws using the specified torque.
If the module is not properly installed, it may result in malfunctions, failure, or fallout.
- Verify that the external device connector, SSCNET connector and RS-422 connector are securely attached to the connectors on the module. Confirm that they connect with an audible click.
If not attached properly, a contact error may occur, resulting in incorrect input or output.
- Always attach a cover to connectors that are not used. If not covered, malfunctions may occur.
- Do not directly touch the module's conductive parts or electronic components. Doing so could cause malfunction or failure in the module.

[WIRING PRECAUTIONS]

CAUTION

- Be sure there are no foreign substances such as sawdust or wiring debris inside the module.
Such debris could cause fires, failure, or malfunction.
- Perform soldering of the external device connector and SSCNET connector after verifying the pin layout.
- Perform soldering of those connectors correctly. False soldering may cause short circuits and malfunctions.

[STARTUP AND MAINTENANCE PRECAUTIONS]

DANGER

- Make sure to switch all phases of the external power supply off before cleaning.
If you do not switch off the external power supply, it will cause malfunctions of the module.
- Do not disassemble or modify the modules. Doing so could cause failure, malfunction, injury, or fire.
- Make sure to switch all phases of the external power supply off before mounting or removing the module. If you do not switch off the external power supply, it will cause failure or malfunction of the module.
- Remove the external device connector and SSCNET connector after the system has been stopped.
The system will stop if they are removed while the system is running.
- When performing test operation, set the parameter for the speed limit value to a slow setting and prepare for an immediate stop of the module should a dangerous condition occur during operation verification.

[USAGE PRECAUTIONS]

CAUTION

- Exercise caution when the reference-axis speed for interpolation operation has been specified, since the speed of the opposite axis (second axis) can get greater than the set speed (speed limit value).

[DISPOSAL PRECAUTIONS]

CAUTION

- When disposing of this product, treat it as industrial waste.

About the Manuals

The following product are available for this equipment.
Refer to the table given below to choose suitable manuals.

Detailed Manual

Manual name	Manual No. (Model code)
Positioning module type A1SD75M1/M2/M3, AD75M1/M2/M3 User's Manual	IB-66715 (13J870)

Related Manual

Manual name	Manual No. (Model code)
Positioning module software package type SW1IVD-AD75P Operating Manual	IB-66714 (13J915)
GX Configurator-AP Version 1 Operating Manual	IB-66900 (13J948)

Correspondence to EMC DIRECTIVE

For instructions to make the PLC compatible with EMC standards, refer to "EMC AND LOW-VOLTAGE DIRECTIVE" in PLC CPU User's Manual (Hardware).

* When the PLC CPU user's manual (Hardware) does not include Chapter 3 "EMC AND LOW-VOLTAGE DIRECTIVE", refer to QnA Series CPU Compatible High-Speed Accessing Basic Base Unit-Additional Explanation for Product Conforming to EMC Standards (IB-68837) (optional).

1. Overview

This manual describes how to install AD75M1/M2/M3 Positioning Module (hereafter abbreviated as AD75) and how to wire them with external devices.

After unpacking AD75, please confirm that the following products are contained.

Product name		Quantity		
AD75M1 Positioning Module		1		
AD75M2 Positioning Module			1	
AD75M3 Positioning Module				1
External device connector (Model)	Connector (10136-3000VE)	1	2	3
	Connector cover (10336-56F0-008)	1	2	3

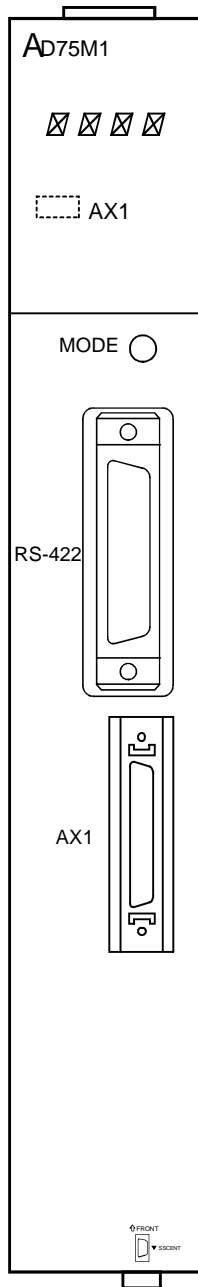
2. Performance Specifications

The performance specifications for the AD75 are shown below.

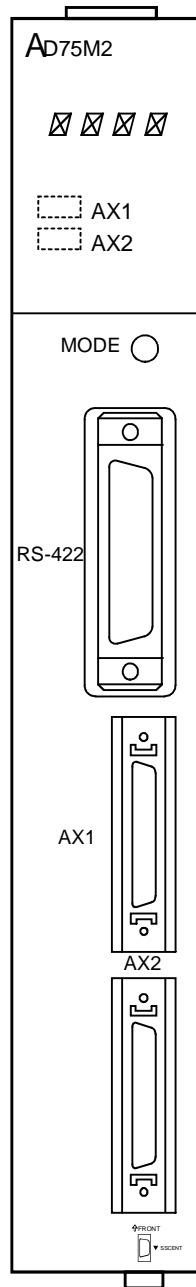
Item	Specifications
Maximum output command speed	1Mpps
Maximum connection distance between servos	Overall distance of SSCNET cable: 30m (98.43 ft.)
Number of occupied I/O points	32 points
Internal current consumption	5VDC, 0.7A or less
Flash ROM write counts	Max. 100,000 times
Access counts to the FeRAM when the absolute position detection system is employed	Max. 9,999,900,000 times
External dimensions (mm)[inch]	250[9.84](H)×37.5[1.48](W)×106[4.17](D)
Weight (kg)[lb]	0.45[0.99]

3. Names of Each Part

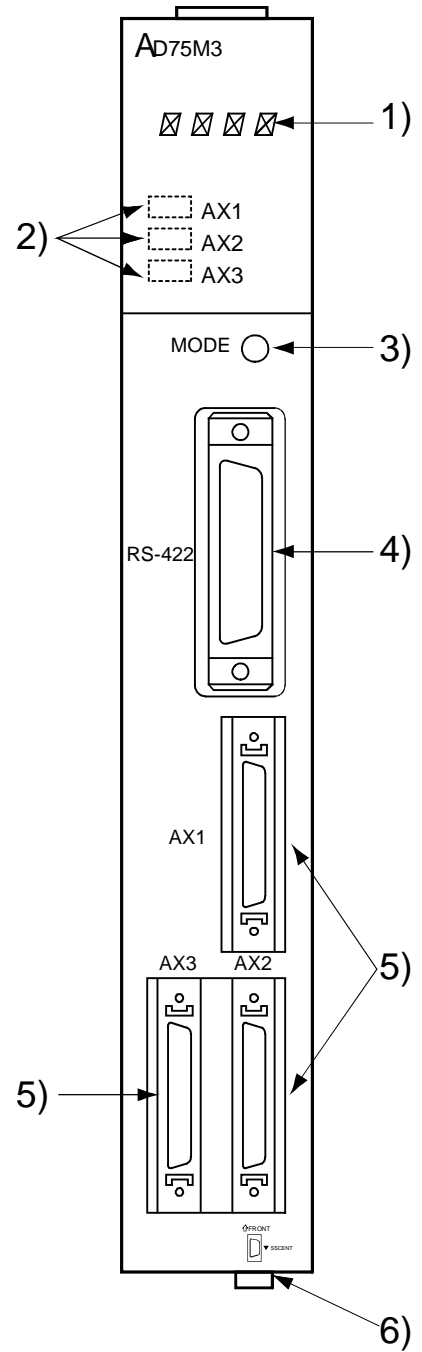
The following shows the name of each part.



AD75M1 front view



AD75M2 front view



AD75M3 front view

No.	Name	Description
1)	17-segment LED	<ul style="list-style-type: none"> • Indicates the operation status. • When the mode switch is pressed, it displays a message for the selected mode.
2)	Axis display LEDs AX1 to 3	<ul style="list-style-type: none"> • Indicate the status of respective axes based on the message displayed on the 17-segment LED.
3)	Mode switch	<ul style="list-style-type: none"> • A selector switch that changes the mode. • The mode is changed each time the switch is pressed.
4)	RS-422 connector	<ul style="list-style-type: none"> • Connector for connection to peripheral device.
5)	External device connector	<ul style="list-style-type: none"> • Connector for mechanical system input or manual pulsar. <p>The applicable wire size for the connector is AWG #24 to #30 (0.05 to 0.2).</p> <p>The pin layout for the included external device connector is as follows. Perform wiring according to the interface.</p> <div data-bbox="794 891 1308 1339" data-label="Diagram"> <p>The diagram illustrates the external device connector. On the left, a top view shows a rectangular connector with 36 pins arranged in two rows of 18. The pins are numbered 1 through 36. A dashed line indicates the wiring path. On the right, a side view shows a wire being inserted into a pin and soldered. Labels 'Wire' and 'Solder' are present.</p> </div> <p>The pin layout viewed from the top is shown. The connector pins are referred to as 1 to 36.</p>
6)	SSCNET connector	Connector for SSCNET-compatible servo amplifier

4. Loading and Installation

The following is explanations of the handling precautions and installation environment which is common to modules when handling AD75 from unpacking to installation. For the details of loading and installation of the module, refer to User's Manual of PLC CPU module to be used.

4.1 Handling precautions

- (1) Because the case of the module is made of resin, be careful not to drop it or expose it to strong impact.
- (2) Do not remove the printed circuit board of the module from the case. This may cause malfunctions.
- (3) Be careful not to let foreign matters such as filings or wire chips get inside the module during wiring. When such matters do enter, be sure to remove them.
- (4) Execute tightening of the module's installation screws within the range indicated below.

Screw position	Tightening torque range
Module fixing screw (M4 screw)	78 to 118 Ncm (6.9 to 10.4 lb•inch)

4.2 Installation environment

Do not install the A series PLC in the following environments.

- (1) Where the ambient temperature exceeds the 0 to 55°C range.
- (2) Where the ambient humidity exceeds the 10 to 90 % RH range.
- (3) Where condensation is produced by sudden temperature changes.
- (4) Where corrosive or combustible gas is present.
- (5) Where dust, iron powder and other conductive powder, oil mist, salt, or organic solvents are prevalent.
- (6) In direct sunlight.
- (7) Where a strong electric or magnetic field is generated.
- (8) Where vibration and shock may be transmitted directly to the module.

5. Wiring

Precautionary notes when wiring as well as the interface are described below.

5.1 Precautionary notes when wiring

This section describes the precautionary notes for the wiring process between the AD75 and outside (servo amplifier).

(1) Signal wiring

- (a) Do not bundle I/O signal wires with, or lay them close to, power lines or main circuit lines.
- (b) If I/O signal wires have to be laid close to these lines, either use a partitioned duct or separate conduits.
- (c) If there is no alternative but to bundle the cables together, use a shielded cable and ground its shielding at the PLC CPU side.
- (d) If conduits are used for wiring, ground the conduits.
- (e) If the connecting cable is too long, or is too close to a main circuit line, malfunctions could occur due to noise.

(2) Fitting connectors to the AD75

- (a) Make sure that the external device connector, connector for connection to the SSCNET, and connector for connecting the peripheral device, are securely engaged with the corresponding connector at the AD75, and have clicked into place.

If the connector is not engaged securely the contact will be defective, and this could cause erroneous inputs and outputs.

- (b) Disconnect the external device connector and SSCNET connector while the system is stopped.

If these connectors are disconnected while the system is in operation, the system will stop.

Note) Refer to Servo Amplifier Instruction Manual for the cable and terminal connector that are required for connection to a servo amplifier in SSCNET.

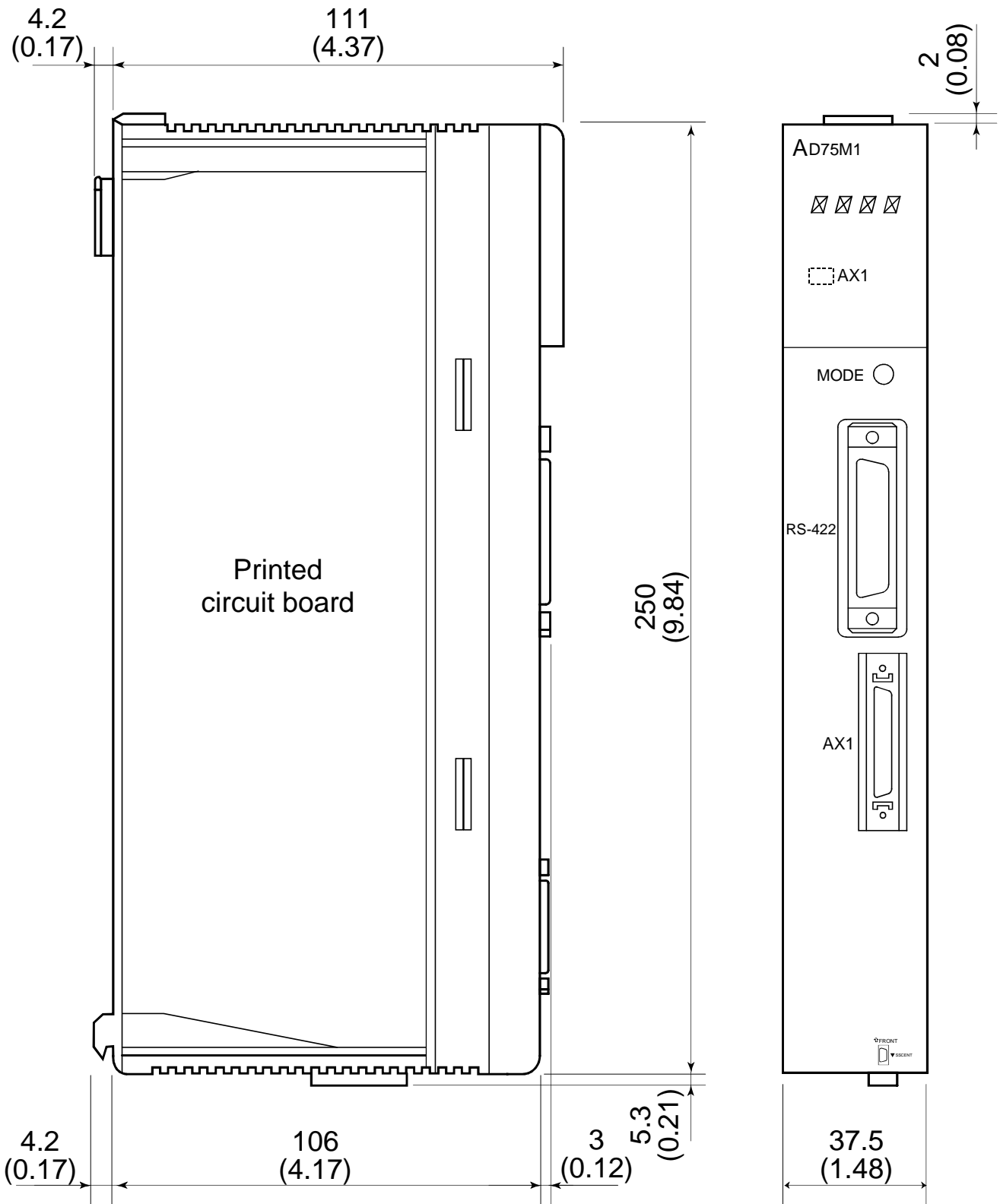
5.2 Interface

○ : Wiring required △ : Wiring performed as required

External wiring	Pin number	Internal circuit	Signal name	Wiring requirement	
<p>When the high limit LS is not used</p> <p>When the low limit LS is not used</p> <p>24VDC</p> <p>5V</p> <p>5VDC</p> <p>A</p> <p>B</p> <p>OV</p> <p>Manual pulser (MR-HDP01)</p>	11		Near-point dog signal DOG	△	
	12		High limit LS signal FLS	○	
	13		Low limit LS signal RLS	○	
	14		Stop signal STOP	△	
	15		Speed/position switch signal CHG	△	
	16		External start signal STRT	△	
	35		Common COM	○	
	36				
	<p>5VDC</p> <p>Manual pulser (MR-HDP01)</p>	(+) 9		Manual pulser phase A PULSER A+	△
		(-) 27		Manual pulser phase A PULSER A-	
(+) 10			Manual pulser phase B PULSER B+		
(-) 28			Manual pulser phase B PULSER B-		

6. External Dimensions

AD75M1 is shown.



Unit:mm(inch)

* External dimensions are the same for AD75M1, M2 and M3.

Warranty

Mitsubishi will not be held liable for damage caused by factors found not to be the cause of Mitsubishi; machine damage or lost profits caused by faults in the Mitsubishi products; damage, secondary damage, accident compensation caused by special factors unpredictable by Mitsubishi; damages to products other than Mitsubishi products; and to other duties.

For safe use

- This product has been manufactured as a general-purpose part for general industries, and has not been designed or manufactured to be incorporated in a device or system used in purposes related to human life.
- Before using the product for special purposes such as nuclear power, electric power, aerospace, medicine or passenger movement vehicles, consult with Mitsubishi.
- This product has been manufactured under strict quality control. However, when installing the product where major accidents or losses could occur if the product fails, install appropriate backup or failsafe functions in the system.

Country/Region	Sales office/Tel	Country/Region	Sales office/Tel
U.S.A	Mitsubishi Electric Automation Inc. 500 Corporate Woods Parkway Vernon Hills, IL 60061 Tel : +1-847-478-2100	China	Ryoden International Shanghai Ltd. 3F Block5 Building Automation Instrumentation Plaza 103 Cao Bao Rd. Shanghai 200233 China Tel : +86-21-6475-3228
Brazil	MELCO-TEC Rep. Com.e Assessoria Tecnica Ltda. Av. Rio Branco, 123-15 ,and S/1507, Rio de Janeiro, RJ CEP 20040-005, Brazil Tel : +55-21-221-8343	Taiwan	Setsuyo Enterprise Co., Ltd. 6F., No.105 Wu-Kung 3rd.RD, Wu-Ku Hsiang, Taipei Hsine, Taiwan Tel : +886-2-2299-2499
Germany	Mitsubishi Electric Europe B.V. German Branch Gothaer Strasse 8 D-40880 Ratingen, GERMANY Tel : +49-2102-486-0	Korea	HAN NEUNG TECHNO CO.,LTD. 1F Dong Seo Game Channel Bldg., 660-11, Deungchon-dong Kangsec-ku, Seoul, Korea Tel : +82-2-3668-6567
U.K	Mitsubishi Electric Europe B.V. UK Branch Travellers Lane, Hatfield, Herts., AL10 8XB,UK Tel : +44-1707-276100	Singapore	Mitsubishi Electric Asia Pte, Ltd. 307 ALEXANDRA ROAD #05-01/02, MITSUBISHI ELECTRIC BUILDING SINGAPORE 159943 Tel : +65-473-2480
Italy	Mitsubishi Electric Europe B.V. Italian Branch Centro Dir. Colleoni, Pal. Perseo - Ingr.2 Via Paracelso 12, 20041 Agrate B., Milano, Italy Tel:+39-039-6053301	Thailand	F. A. Tech Co.,Ltd. 898/28,29,30 S.V.City Building,Office Tower 2,Floor 17-18 Rama 3 Road, Bangkokpong, Yannawa, Bangkok 10120 Tel : +66-2-682-6522
Spain	Mitsubishi Electric Europe B.V. Spanish Branch Carretera de Rubi 76-80 08190 - Sant Cugat del Valles, Barcelona, Spain Tel:+34-935-653135	Indonesia	P.T. Autoteknindo SUMBER MAKMUR Jl. Muara Karang Selatan Block A Utara No.1 Kav. No.11 Kawasan Industri/ Pergudangan Jakarta - Utara 14440 Tel : +62-21-663-0833
South Africa	Circuit Breaker Industries LTD. Private Bag 2016, Isando 1600, Johannesburg, South Africa Tel : +27-11-928-2000	India	Messung Systems Put,Ltd. Electronic Sadan NO:111 Unit No15, M.I.D.C BHOSARI,PUNE-411026 Tel : +91-20-7128927
Hong Kong	Ryoden International Ltd. 10th Floor, Manulife Tower, 169 Electric Road, North Point, HongKong Tel : +852-2887-8870	Australia	Mitsubishi Electric Australia Pty. Ltd. 348 Victoria Road, PostalBag, No 2, Rydalmere, N.S.W 2116, Australia Tel : +61-2-9684-7777

MITSUBISHI ELECTRIC CORPORATION

HEAD OFFICE : 1-8-12, OFFICE TOWER Z 14F HARUMI CHUO-KU 104-6212, JAPAN
NAGOYA WORKS : 1-14, YADA-MINAMI5, HIGASHI-KU, NAGOYA, JAPAN

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HEADQUARTERS

MITSUBISHI ELECTRIC EUROPE B.V. **EUROPE**
 German Branch
 Gothaer Straße 8
D-40880 Ratingen
 Phone: +49 (0)2102 / 486-0
 Fax: +49 (0)2102 / 486-1120

MITSUBISHI ELECTRIC EUROPE B.V.-org.sl. **CZECH REP.**
 Czech Branch
 Avenir Business Park, Radlická 714/113a
CZ-158 00 Praha 5
 Phone: +420 - 251 551 470
 Fax: +420 - 251-551-471

MITSUBISHI ELECTRIC EUROPE B.V. **FRANCE**
 French Branch
 25, Boulevard des Bouvets
F-92741 Nanterre Cedex
 Phone: +33 (0)1 / 55 68 55 68
 Fax: +33 (0)1 / 55 68 57 57

MITSUBISHI ELECTRIC EUROPE B.V. **IRELAND**
 Irish Branch
 Westgate Business Park, Ballymount
IRL-Dublin 24
 Phone: +353 (0)1 4198800
 Fax: +353 (0)1 4198890

MITSUBISHI ELECTRIC EUROPE B.V. **ITALY**
 Italian Branch
 Viale Colleoni 7
I-20041 Agrate Brianza (MB)
 Phone: +39 039 / 60 53 1
 Fax: +39 039 / 60 53 312

MITSUBISHI ELECTRIC EUROPE B.V. **POLAND**
 Poland Branch
 Krakowska 50
PL-32-083 Balice
 Phone: +48 (0)12 / 630 47 00
 Fax: +48 (0)12 / 630 47 01

MITSUBISHI ELECTRIC EUROPE B.V. **RUSSIA**
 52, bid. 3 Kosmodamianskaya nab 8 floor
RU-115054 Moscow
 Phone: +7 495 721-2070
 Fax: +7 495 721-2071

MITSUBISHI ELECTRIC EUROPE B.V. **SPAIN**
 Spanish Branch
 Carretera de Rubí 76-80
E-08190 Sant Cugat del Vallés (Barcelona)
 Phone: 902 131121 // +34 935653131
 Fax: +34 935891579

MITSUBISHI ELECTRIC EUROPE B.V. **UK**
 UK Branch
 Travellers Lane
UK-Hatfield, Herts. AL10 8XB
 Phone: +44 (0)1707 / 27 61 00
 Fax: +44 (0)1707 / 27 86 95

MITSUBISHI ELECTRIC CORPORATION **JAPAN**
 Office Tower "Z" 14 F
 8-12,1 chome, Harumi Chuo-Ku
Tokyo 104-6212
 Phone: +81 3 622 160 60
 Fax: +81 3 622 160 75

MITSUBISHI ELECTRIC AUTOMATION, Inc. **USA**
 500 Corporate Woods Parkway
Vernon Hills, IL 60061
 Phone: +1 847 478 21 00
 Fax: +1 847 478 22 53

EUROPEAN REPRESENTATIVES

GEVA **AUSTRIA**
 Wiener Straße 89
AT-2500 Baden
 Phone: +43 (0)2252 / 85 55 20
 Fax: +43 (0)2252 / 488 60

TEHNIKON **BELARUS**
 Oktyabrskaya 16/5, Off. 703-711
BY-220030 Minsk
 Phone: +375 (0)17 / 210 46 26
 Fax: +375 (0)17 / 210 46 26

ESCO DRIVES & AUTOMATION **BELGIUM**
 Culliganlaan 3
BE-1831 Diegem
 Phone: +32 (0)2 / 717 64 30
 Fax: +32 (0)2 / 717 64 31

Koning & Hartman b.v. **BELGIUM**
 Woluwelaan 31
BE-1800 Vilvoorde
 Phone: +32 (0)2 / 257 02 40
 Fax: +32 (0)2 / 257 02 49

INEA BH d.o.o. **BOSNIA AND HERZEGOVINA**
 Aleja Lipa 56
BA-71000 Sarajevo
 Phone: +387 (0)33 / 921 164
 Fax: +387 (0)33 / 524 539

AKHNATON **BULGARIA**
 4 Andrej Ljapchev Blvd. Pb 21
BG-1756 Sofia
 Phone: +359 (0)2 / 817 6044
 Fax: +359 (0)2 / 97 44 06 1

INEA CR d.o.o. **CROATIA**
 Losinjska 4 a
HR-10000 Zagreb
 Phone: +385 (0)1 / 36 940 -01 / -02 / -03
 Fax: +385 (0)1 / 36 940 -03

AutoCont C.S. s.r.o. **CZECH REPUBLIC**
 Technologická 374/6
CZ-708 00 Ostrava-Pustkovce
 Phone: +420 595 691 150
 Fax: +420 595 691 199

Beijer Electronics A/S **DENMARK**
 Lykkegårdsvej 17
DK-4000 Roskilde
 Phone: +45 (0)46 / 75 76 66
 Fax: +45 (0)46 / 75 56 26

Beijer Electronics Eesti OÜ **ESTONIA**
 Pärnu mnt.160i
EE-11317 Tallinn
 Phone: +372 (0)6 / 51 81 40
 Fax: +372 (0)6 / 51 81 49

Beijer Electronics OY **FINLAND**
 Peltoie 37
FIN-28400 Ulvila
 Phone: +358 (0)207 / 463 540
 Fax: +358 (0)207 / 463 541

UTEKO **GREECE**
 5, Mavrogenous Str.
GR-18542 Piraeus
 Phone: +30 211 / 1206 900
 Fax: +30 211 / 1206 999

MELTRADE Kft. **HUNGARY**
 Fertő utca 14.
HU-1107 Budapest
 Phone: +36 (0)1 / 431-9726
 Fax: +36 (0)1 / 431-9727

Beijer Electronics SIA **LATVIA**
 Rītausmas iela 23
LV-1058 Rīga
 Phone: +371 (0)784 / 2280
 Fax: +371 (0)784 / 2281

Beijer Electronics UAB **LITHUANIA**
 Savanorių Pr. 187
LT-02300 Vilnius
 Phone: +370 (0)5 / 232 3101
 Fax: +370 (0)5 / 232 2980

EUROPEAN REPRESENTATIVES

ALFATRADE Ltd. **MALTA**
 99, Paola Hill
Malta- Paola PLA 1702
 Phone: +356 (0)21 / 697 816
 Fax: +356 (0)21 / 697 817

INTEHSIS srl **MOLDOVA**
 bld. Traian 23/1
MD-2060 Kishinev
 Phone: +373 (0)22 / 66 4242
 Fax: +373 (0)22 / 66 4280

HIFLEX AUTOM.TECHNIEK B.V. **NETHERLANDS**
 Wolweverstraat 22
NL-2984 CD Ridderkerk
 Phone: +31 (0)180 - 46 60 04
 Fax: +31 (0)180 - 44 23 55

Koning & Hartman b.v. **NETHERLANDS**
 Haarderbergweg 21-23
NL-1101 CH Amsterdam
 Phone: +31 (0)20 / 587 76 00
 Fax: +31 (0)20 / 587 76 05

Beijer Electronics AS **NORWAY**
 Postboks 487
NO-3002 Drammen
 Phone: +47 (0)32 / 24 30 00
 Fax: +47 (0)32 / 84 85 77

Fonseca S.A. **PORTUGAL**
 R. João Francisco do Casal 87/89
PT - 3801-997 Aveiro, Esgueira
 Phone: +351 (0)234 / 303 900
 Fax: +351 (0)234 / 303 910

Sirius Trading & Services srl **ROMANIA**
 Aleea Lacul Morii Nr. 3
RO-060841 Bucuresti, Sector 6
 Phone: +40 (0)21 / 430 40 06
 Fax: +40 (0)21 / 430 40 02

Craft Con. & Engineering d.o.o. **SERBIA**
 Bulevar Svetog Cara Konstantina 80-86
SER-18106 Nis
 Phone: +381 (0)18 / 292-24-4/5
 Fax: +381 (0)18 / 292-24-4/5

INEA SR d.o.o. **SERBIA**
 Izletnicka 10
SER-113000 Smederevo
 Phone: +381 (0)26 / 617 163
 Fax: +381 (0)26 / 617 163

SIMAP s.r.o. **SLOVAKIA**
 Jána Derku 1671
SK-911 01 Trenčín
 Phone: +421 (0)32 743 04 72
 Fax: +421 (0)32 743 75 20

PROCONT, spol. s r.o. Prešov **SLOVAKIA**
 Kúpeľná 1/A
SK-080 01 Prešov
 Phone: +421 (0)51 7580 611
 Fax: +421 (0)51 7580 650

INEA d.o.o. **SLOVENIA**
 Stegne 11
SI-1000 Ljubljana
 Phone: +386 (0)1 / 513 8100
 Fax: +386 (0)1 / 513 8170

Beijer Electronics AB **SWEDEN**
 Box 426
SE-20124 Malmö
 Phone: +46 (0)40 / 35 86 00
 Fax: +46 (0)40 / 93 23 01

Omni Ray AG **SWITZERLAND**
 Im Schörl 5
CH-8600 Dübendorf
 Phone: +41 (0)44 / 802 28 80
 Fax: +41 (0)44 / 802 28 28

GTS **TURKEY**
 Bayraktar Bulvarı Nutuk Sok. No:5
TR-34775 Yukarı Dudullu-Ümraniye-İSTANBUL
 Phone: +90 (0)216 526 39 90
 Fax: +90 (0)216 526 39 95

CSC Automation Ltd. **UKRAINE**
 4-B, M. Raskovoyi St.
UA-02660 Kiev
 Phone: +380 (0)44 / 494 33 55
 Fax: +380 (0)44 / 494-33-66

EURASIAN REPRESENTATIVES

Kazpromautomatiks Ltd. **KAZAKHSTAN**
 Mustafina Str. 7/2
KAZ-470046 Karaganda
 Phone: +7 7212 / 50 11 50
 Fax: +7 7212 / 50 11 50

MIDDLE EAST REPRESENTATIVES

ILAN & GAVISH Ltd. **ISRAEL**
 24 Shenkar St., Kiryat Arie
IL-49001 Petah-Tiqva
 Phone: +972 (0)3 / 922 18 24
 Fax: +972 (0)3 / 924 0761

TEXEL ELECTRONICS Ltd. **ISRAEL**
 2 Ha'umanut, P.O.B. 6272
IL-42160 Netanya
 Phone: +972 (0)9 / 863 39 80
 Fax: +972 (0)9 / 885 24 30

CEG INTERNATIONAL **LEBANON**
 Cebaco Center/Block A Autostrade DORA
Lebanon - Beirut
 Phone: +961 (0)1 / 240 430
 Fax: +961 (0)1 / 240 438

AFRICAN REPRESENTATIVE

CBI Ltd. **SOUTH AFRICA**
 Private Bag 2016
ZA-1600 Isando
 Phone: +27 (0)11 / 977 0770
 Fax: +27 (0)11 / 977 0761