

MITSUBISHI

PROGRAMMABLE CONTROLLER

MELSEC-A

User's Manual

Positioning module type A1SD75P1/P2/P3 (Hardware)

INTRODUCTION

Thank you for choosing the Mitsubishi MELSEC-A Series of General Purpose Programmable Controllers. Please read this manual carefully so that the equipment is used to its optimum. A copy of this manual should be forwarded to the end User.



IB (NA) 66584-A

Cautions on Safety

(Please read before using the module)


Please carefully read this manual and related ones mentioned herein to ensure safety and operate this module properly.

The following cautions are applicable only to the module. For the cautions on safety relating to the PC CPU system, see the PC CPU User's Manual.


The cautions in this cautions on safety are classified into two ranks, "DANGER" and "CAUTION", according to their importance.

 DANGER

A warning given when improper operation could result in a dangerous situation causing death or serious injuries.

 CAUTION

A caution given when improper operation could result in a dangerous situation causing moderate or injuries, and physical damage to the module, etc.

Even failure to observe a caution marked  CAUTION may bring about a serious accident depending on the situation. Do not fail to follow the cautions. Retain this manual for consultation whenever necessary, and provide a copy to the end user.

Cautions on Design

 DANGER


• To ensure that the system as a whole will continue to operate safely even if there is a fault in the external power supply or in the PC itself, provide a safety circuit external to the PC. Otherwise, accidents may be caused by erroneous outputs and malfunctions.

- (1) Construct interlock circuitry to prevent damage to the machine, such as an emergency stop circuit, positioning upper/lower limit interlock, etc., external to the PC.
- (2) Home position return operations are controlled by two data: the home position return direction and the home position return speed and deceleration starts when the near point dog comes ON. Consequently, if an incorrect home position return direction is set, motion may continue without deceleration. To prevent damage to the machine if this happens, construct a circuit such as an interlock circuit external to the PC.
- (3) When the module detects an error, a normal deceleration to stop or emergency stop is executed in accordance with the setting for stop group n in the parameters. Match the parameter settings to the system specifications. Also, set home position return data and positioning data with values no greater than the values specified in the parameters.

 CAUTION

• Do not bundle the control wire and the communication cable with the main circuit or power line or keep them close to one another. Keep the control wire and the communication cable at least 100 mm away from the main circuit or power line; otherwise, noise or malfunctions will occur.

Cautions on Installation

 CAUTION

- Use the PC in the environment specified in the General Specifications section in this manual. Using it in an environment which does not meet the general specifications could cause electric shock, fire or malfunctions, and damage or deterioration of the module.
- Install the module by engaging the module mounting projections on the lower part of the module in the mounting holes of the base unit. Incorrect installation could result in malfunctions, failure of detachment.
- Engage the drive unit connector and peripheral device connector securely with the connectors on the module; you will hear a click on engagement. Failure to engage the connectors properly could result in a faulty connection, leading to erroneous inputs and outputs.
- If no drive unit is connected, be sure to fit the cover on the connector. Failure to fit the cover could result in malfunctions.

Cautions on Wiring

 CAUTION

- Carry out wiring to the module correctly, checking the terminal arrangement.
- Take all possible measures to prevent chips or wire scraps from entering the module. Entry of foreign material will cause fire, failure or malfunctions.

| | |
|--------------------------|--|
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Specifications subject to change without notice.

Cautions on Start-Up and Maintenance


| |
|--|
|  DANGER |
| <ul style="list-style-type: none"> Switch the power off before cleaning the module. If the power is left on, the module will break down or malfunction. |

| |
|---|
|  CAUTION |
| <ul style="list-style-type: none"> Do not disassemble or tamper with the module. This will cause failure, malfunctions, injuries or fire. Switch the power off before installing or removing the module. If the power is left on, the module will break down or malfunction. For test operation, set lower speed restriction values in the parameters and make sure that motion can be stopped immediately in the event of any hazard before starting the operation. |

Cautions on Method of Use

| |
|---|
|  CAUTION |
| <ul style="list-style-type: none"> When specifying the speed for the reference axis in an interpolation operation, note that the speed for the corresponding axis (second axis) may be greater than the set speed (i.e. greater than the speed restriction). |

Caution on Disposal

| |
|--|
|  CAUTION |
| <ul style="list-style-type: none"> Dispose of the module as industrial waste. |

1. GENERAL DESCRIPTION

1. GENERAL DESCRIPTION

This manual explains the specifications, names of parts, and I/O interface of the A1SD75P1/P2/P3 positioning module.

On unpacking the A1SD75, check that the following items have been supplied.

| Part Name | Quantity | | |
|---|----------|---|---|
| Type A1SD75P1 positioning module | 1 | | |
| Type A1SD75P2 positioning module | | 1 | |
| Type A1SD75P3 positioning module | | | 1 |
| Connector for external wiring (made by Sumitomo 3M) (Model name) | | | |
| Connector 10136-3000VE | 1 | 2 | 3 |
| Connector cover 10336 56F0 008 | 1 | 2 | 3 |

The following manuals are also related to this product. If necessary, order them by quoting the details in the tables below.

- Detailed Manual A1SD75P1/P2/P3, AD75P1/P2/P3 User's Manual (IB-66589)

2. PERFORMANCE SPECIFICATIONS

2. PERFORMANCE SPECIFICATIONS

| Item | Model | A1SD75P1 | A1SD75P2 | A1SD75P3 |
|---|--|---|--|--|
| Number of control axes | | 1 | 2 | 3 |
| Interpolation | | None | 2-axis linear interpolation 2-axis circular interpolation | 2-axis linear interpolation 2-axis circular interpolation |
| Control method | | PTP control, locus control (both linear and circular can be set) Speed control, Speed/positioning control switching | | |
| Control units | | mm, inch, degree, pulse | | |
| Positioning data | | Peripheral device PC | 600 patterns/axis 100 patterns/axis only can be set. | |
| Peripheral device | | IBM PC/AT or 100% compatible : SW01VD-AD75P | | |
| Backup | | Parameters and positioning data are stored in a flash ROM (no battery required) *1 | | |
| Positioning | Method | PTP control: Incremental method / Absolute method Speed/positioning control switching: Incremental method Locus control: Incremental method / Absolute method | | |
| | Positioning range | For the absolute method | | |
| | | <ul style="list-style-type: none"> -214748364.8 to 214748364.7 (μm) -21474.83648 to 21474.83647 (inch) 0 to 359.99999 (degree) -214748364.8 to 214748364.7 (pulse) | | |
| | | For the incremental method | | |
| | Positioning range | <ul style="list-style-type: none"> -214748364.8 to 214748364.7 (μm) -21474.83648 to 21474.83647 (inch) -21474.83648 to 21474.83647 (inch) -214748364.8 to 214748364.7 (pulse) | | |
| | | For the speed/positioning control switching mode | | |
| Speed commands | <ul style="list-style-type: none"> 0.01 to 600000.00 (mm/min) 0.001 to 600000.000 (inch/min) 0.001 to 600000.000 (degree/min) 1 to 1000000 (pulse/s) | | | |
| | Acceleration and deceleration | Automatic trapezoidal acceleration and deceleration, Automatic S pattern acceleration and deceleration | | |
| Acceleration and deceleration time | 1 to 65535 (ms) 4 patterns can be set for both acceleration and deceleration | | | |
| Deceleration time for emergency stop | 1 to 65535 (ms) | | | |
| Compensation | Electronic gear, backlash compensation | | | |
| Home position return method | Near-zero point dog method, time-out method, stopper method | | | |
| Jog operation function | Provided | | | |
| Manual pulse generator operation function | Provided | | | |
| M code output function | Provided (WITH mode or AFTER mode can be selected) | | | |
| Error indication | 17 segment indicator | | | |
| I/O indication | 17 segment indicator and LED indicators | | | |
| Internal current consumption | 5 VDC, 0.7 A | | | |
| Number of occupied I/O points | 32 points (I/O allocation: special, 32 points) | | | |
| Size (mm)[inch] | 130 [5.12] (H) X 34.5 [1.36] (W) X 93.6 [3.69] (D) | | | |
| Weight (kg)[lb] | 0.35 [0.77] | | | |

*1 The sequence program can be transferred from the buffer memory to a flash ROM (backup possible)

3. I/O INTERFACE

3. I/O INTERFACE

| I/O | External Wiring | Pin No | Internal Wiring | Signal Name | Description | |
|----------|-----------------|--------------------------|---|--|---|---|
| Input | | 7 | | Drive unit ready READY | (1) ON when the drive unit is normal and feed pulses can be accepted (READY status) (2) The AD75 checks the drive unit ready signal: if the ready status has not been established, it outputs a home position return request signal (3) Arrange for drive unit errors that make the unit inoperative, e.g. a control power supply fault, to set this signal OFF (HIGH) (4) Switching this signal OFF (HIGH) during positioning stops the operation. Switching the signal back ON (LOW) will not restart the operation (5) When this signal goes OFF (HIGH), the home position return complete signal also goes OFF (HIGH) | |
| | | 8 | | In-position signal INPOS | (1) Input the in position signal from the drive unit | |
| | | 26 | | Common | The input voltage is 24 VDC | |
| | | 11 | | Near-zero point signal DOG | (1) Used to detect the near-zero point during home position return Comes ON when the near-zero point dog signal is detected (LOW) | |
| | | 12 | | Upper limit LS FLS | (1) This is the limit switch installed at the upper limit of the stroke (2) Positioning stops when it comes ON (3) It is also required for execution of home position return retries | |
| | | 13 | | Lower limit LS RLS | (1) This is the limit switch installed at the lower limit of the stroke (2) Positioning stops when it comes ON (3) It is also required for execution of home position return retries | |
| | | 14 | | Stop signal STOP | (1) Switched ON (LOW) for 4 ms or longer to stop positioning (2) When this signal is input, the AD75 stops the positioning it is executing and switches the start signal (START) OFF (HIGH). After this, positioning will not restart even if the STOP signal is switched from ON (LOW) to OFF (HIGH) | |
| | | 15 | | Control switching signal CHG | (1) Used as the control switching signal in the speed/positioning control switching mode | |
| | | 16 | | External start START | (1) The external start signal is used as the input signal for: 1 External positioning start 2 External speed change request 3 Skip request (2) Set the functions of external signals by parameter setting (3) In order for an external start signal to be effective, it must remain ON for 4 ms or longer | |
| | | 17-18 | | Common | The input voltage is 24 VDC | |
| | | (+) 9 | | Manual pulse generator, phase A PULSER A | Input signal voltage level: 5 V ^{+20%} / _{-10%} HIGH level: Voltage 4.5 V or higher Current 3 mA or higher LOW level: Voltage 1.0 V or lower; Current 0 mA Pulse width: 2 ms or longer Timing: The positioning address changes in the way indicated below in accordance with the pulses from the manual pulse Phase A Phase B Positioning address +1 +2 1 2 If phase A is more advanced than phase B, the positioning address (present value) is incremented | |
| | | (-) 27 | | | | |
| | | (+) 10 | | Manual pulse generator phase B PULSER B | Phase difference: Phase A Phase B 0.5 ms or shorter Input pulse rise time/fall time: 500 μs or less | |
| | | (-) 28 | | | | |
| (24 V) 6 | | Zero phase signal PGO | (1) Used as the home position signal in home position return operations: the zero phase grid signal of the pulse encoder is normally used LOW at zero (2) This signal is used too if the home position return method is the stopper method and the home position return complete signal is input from an external source | | | |
| (5 V) 24 | | | | | | |
| 25 | | Common | The input voltage is 24 VDC/5 VDC | | | |
| Output | | 5 | | Deviation counter clear CLEAR | (1) This signal is output after completion of home position return and resets the accumulated pulses in the deviation counter at the drive unit side Example: Home position return method: stopper method (2) Home position return speed Creep speed Near zero point dog Home position detection signal CLEAR 10 ms (second time) Stop after feed pulse output | |
| | | 23 | | Common | Load voltage: 5 VDC to 24 VDC | |
| | | 1 | | CW Phase A PULSE | Open collector output (5/24 V) | Explanation of the relationship between the mode set by parameter and pulse output Mode selection Forward Reverse CW CCW A φ B φ PULSE SIGN |
| | | 19 | | | | |
| | | 3 | | CW Phase A PULSE | Differential drive equivalent to Am62LS31 | |
| | | 21 | | | | |
| | | 2 | | CCW Phase B SIGN | Open collector output (5/24 V) | |
| 20 | | | | | | |
| 4 | | CCW Phase B SIGN | Differential drive equivalent to Am62LS31 | | | |
| 22 | | | | | | |

4.1.2 Signal name of Internal Information n

Repeatedly pressing the mode switch switches the displayed message in the following sequence

| <Signal name> | <Explanation> |
|---------------|------------------------------------|
| SVON | Servo ON |
| Z-ON | Zero-phase signal |
| ULMT | Upper limit signal |
| LLMT | Lower limit signal |
| S-P | Speed/positioning switching signal |
| KDOG | Near-zero point dog ON |

4.1.3 Explanations of other messages

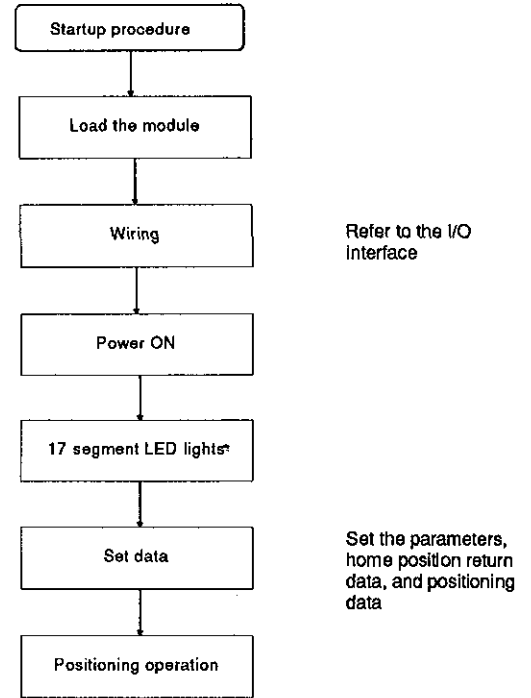
The following messages may be displayed on the 17-segment LED indicator regardless of the mode

| <Message> | <Explanation> |
|-----------|--|
| FALT | Watchdog error or other error has occurred |
| HDOG | Watchdog error or other error has occurred |

6. STARTUP PROCEDURE

6. STARTUP PROCEDURE

The following is a brief guide to the procedure for starting up the A1SD75. For details, see the User's Manuals for the A1SD75P1/P2/P3, AD75P1/P2/P3 models



5. HANDLING

5. HANDLING

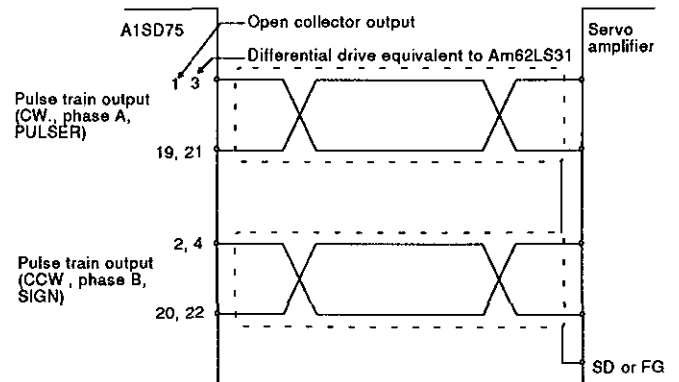
The following handling instructions apply to the A1SD75 in isolation

- (1) The case of the module is made of plastic. Do not drop it or subject it to strong impact.
- (2) Make sure that no conductive debris such as drilling chips enters the module during wiring. If anything does enter the module, remove it.
- (3) Switch off the power to the PC before loading the module on the base or removing it from the base.
- (4) Switch off the power to the PC and drive unit before connecting or disconnecting the drive unit connector. The connector must be engaged in the correct orientation. Check the orientation, and keep it straight and square while connecting it. If no drive unit is connected, the connector cover must be fitted.

7. WIRING PRECAUTIONS

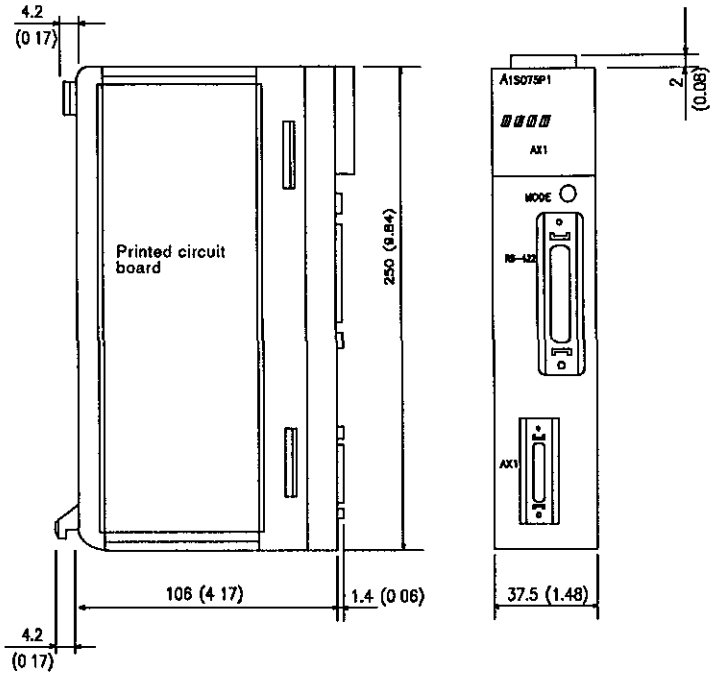
7. WIRING PRECAUTIONS

- (1) If the environment is such that there is likely to be a lot of noise in the wiring connecting the A1SD75 and servo amplifier, use twisted-pair shielded cable - independent of other shielded wiring - for the wiring from the pulse train output terminals of the A1SD75.



8. OUTSIDE DIMENSIONS

8 OUTSIDE DIMENSIONS



Unit: mm(inch)

The A1SD75P1 is shown here

* The outside dimensions are the same for A1SD75P1/P2/P3

REVISION

| | |
|------------|--|
| A | |
| Aug., 1995 | |

IMPORTANT

- (1) Design the configuration of a system to provide an external protective or safety interlocking circuit for the PCs
- (2) The components on the printed circuit boards will be damaged by static electricity, so avoid handling them directly. If it is necessary to handle them take the following precautions:
 - (a) Ground human body and work bench
 - (b) Do not touch the conductive areas of the printed circuit board and its electrical parts with and non-grounded tools etc

Under no circumstances will Mitsubishi Electric be liable or responsible for any consequential damage that may arise as a result of the installation or use of this equipment

All examples and diagrams shown in this manual are intended only as an aid to understanding the text, not to guarantee operation. Mitsubishi Electric will accept no responsibility for actual use of the product based on these illustrative examples.

Owing to the very great variety in possible applications of this equipment, you must satisfy yourself as to its suitability for your specific application.